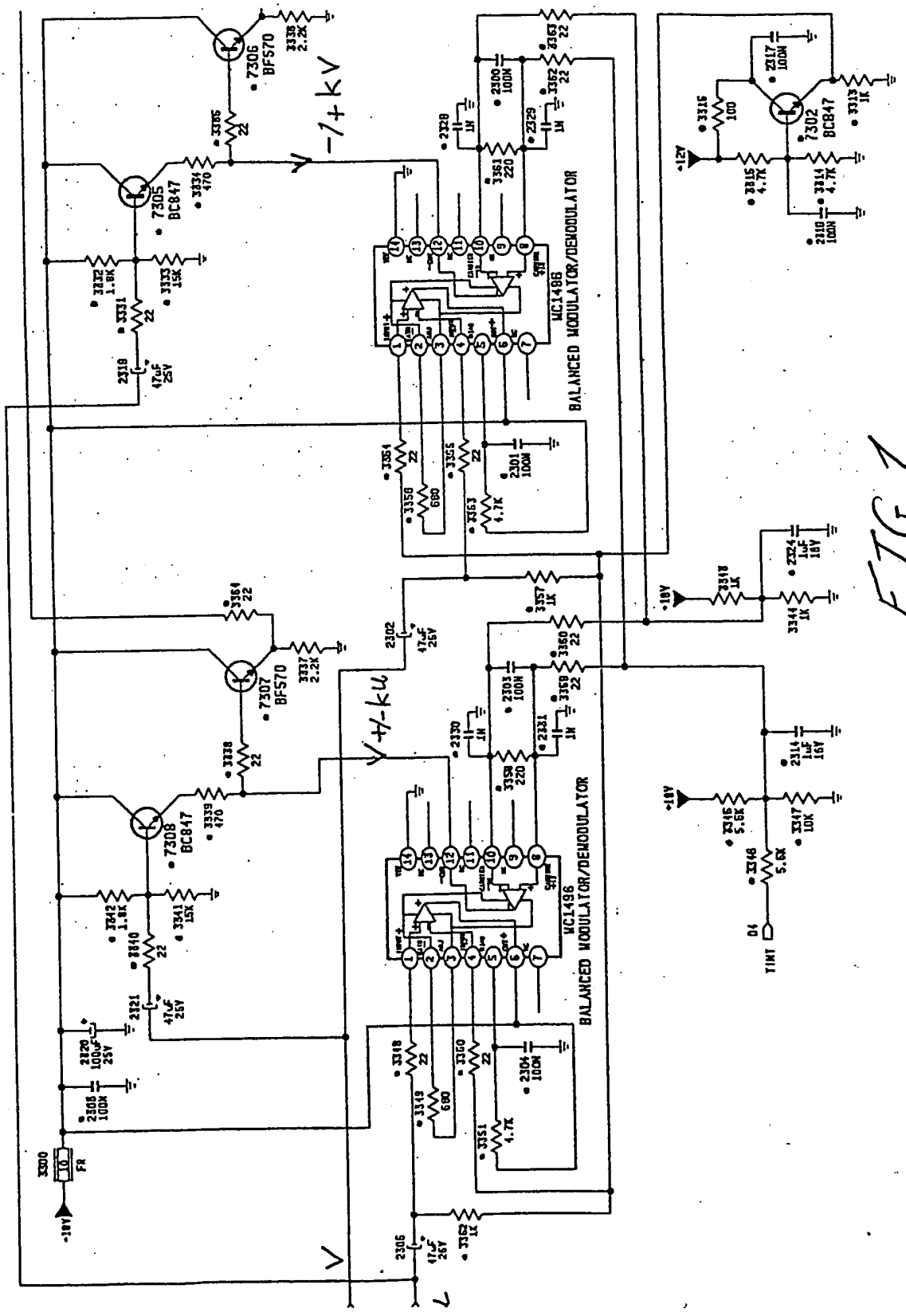

FIG 1 (Prior Art)

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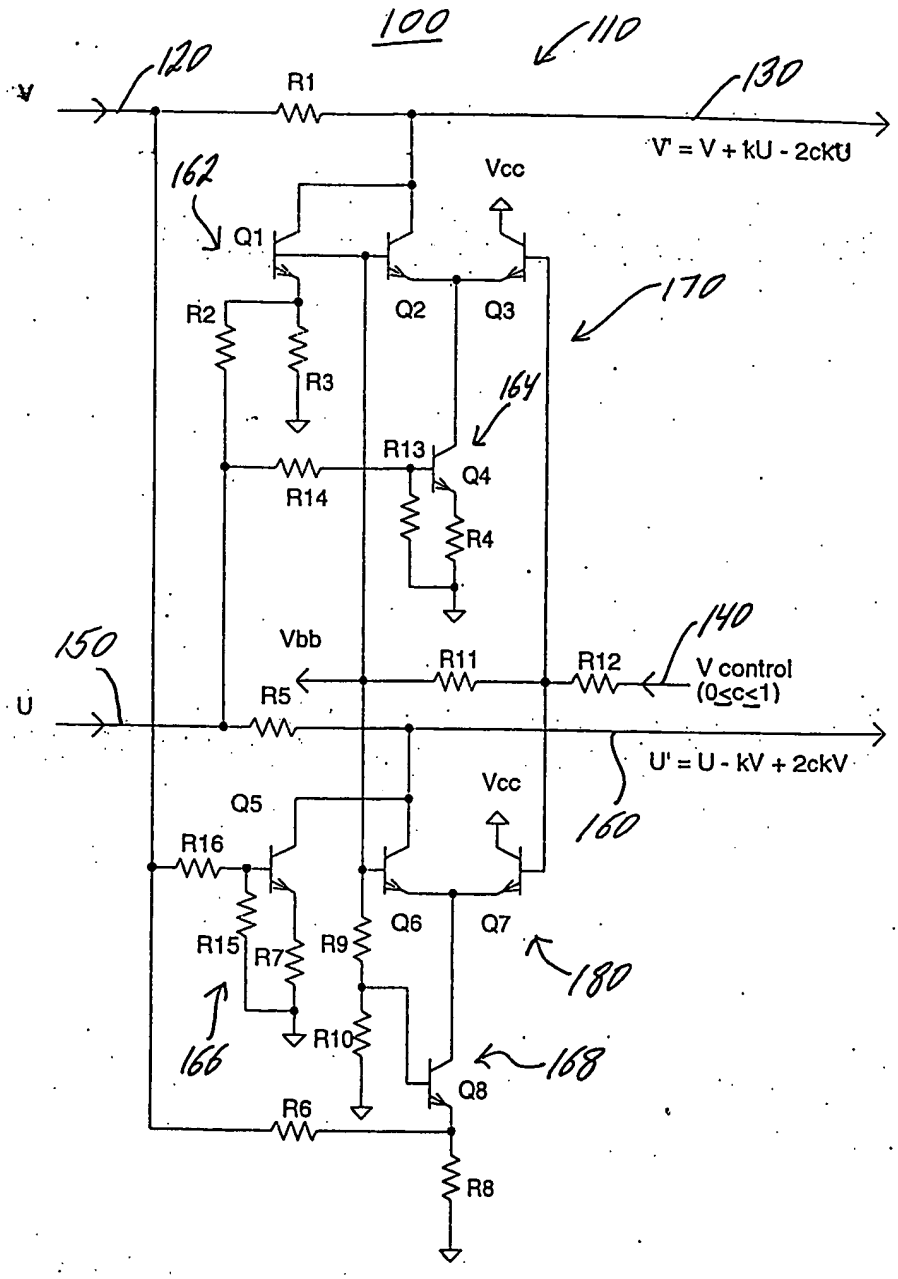
100
110
120
130
V
R1
V' = V + kU - 2ckU
162
Vcc
Q1
Q2
Q3
170
R2
R3
164
R13
Q4
R14
R4
150
Vbb
R11
R12
140
V control
(0≤c≤1)
U
R5
U' = U - kV + 2ckV
160
Vcc
Q5
R16
Q6
Q7
R15
R7
R9
180
166
R10
168
Q8
R6
R8

FIG. 2